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This course provides a mathematical introduction to the mechanics and control of robots that can be modeled as kinematic chains. Topics covered include the concept of a robot 's configuration space and degrees of freedom, static grasp analysis, the description of rigid body motions,

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kinematics of open and closed chains, and
the basics of robot control.

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Mechanical engineering, electrical engineering, or computer science departments. Since its original publication in 1986, Craig's Introduction to Robotics: Mechanics and Control has been the market's leading textbook used for teaching robotics at the university level.

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for understanding mechanics and control theory as it relates to robotics motion. It really gets into the details that books on the subject of computational robots such as "Introduction to Autonomous Mobile Robots" and "Computational Principles of Mobile Robotics" simply do not have the room to accommodate.

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